

Beyond Earth Orbit Trajectory Insertion

“Halfway to Anywhere”

**International Space Development Conference
Toronto, Canada**

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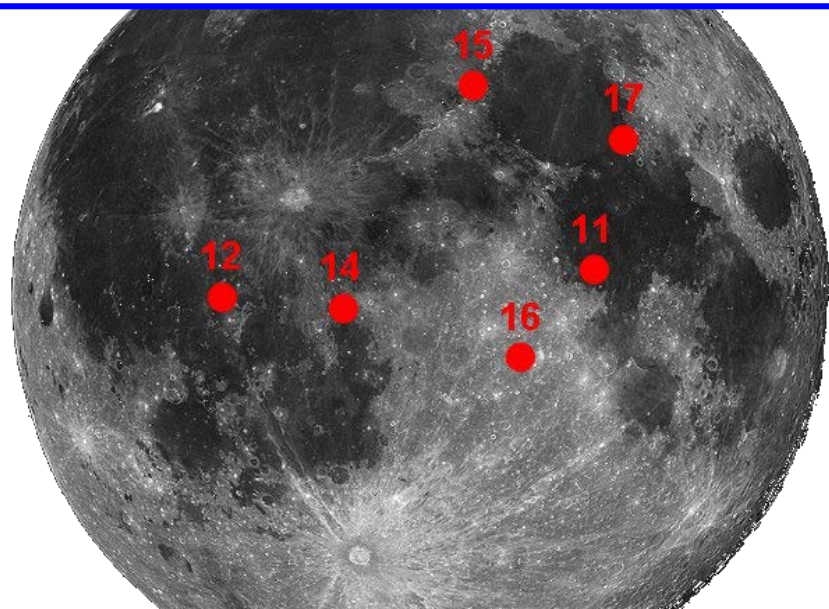
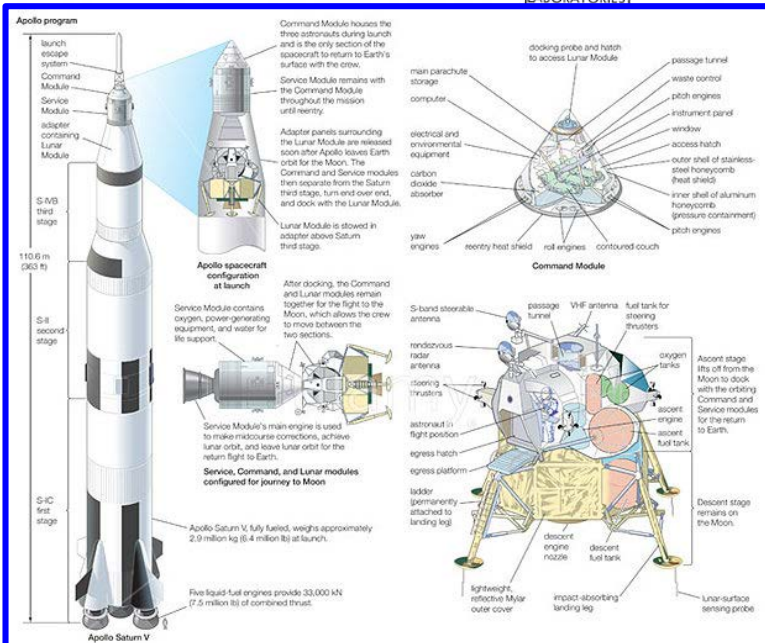
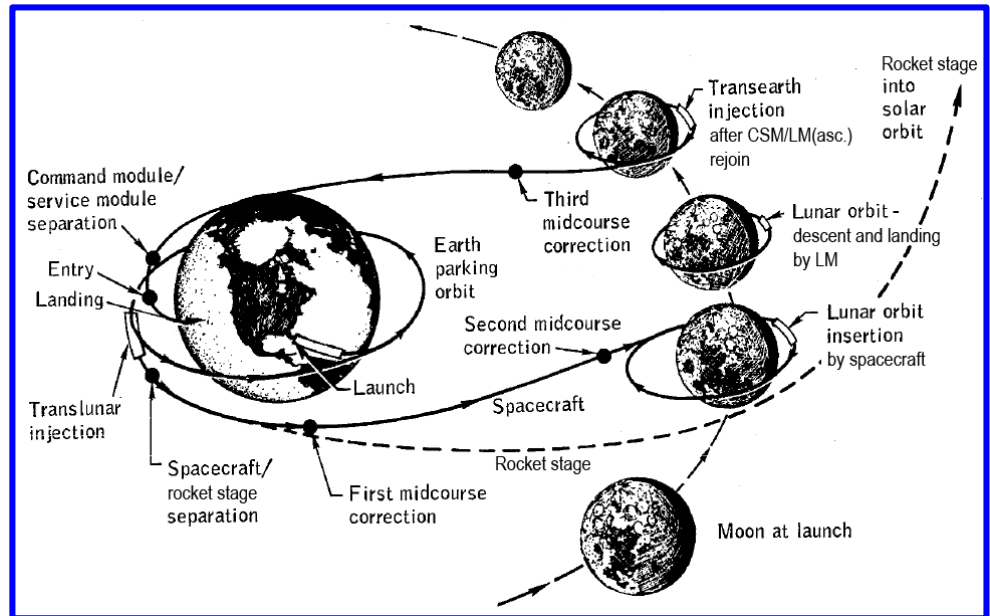
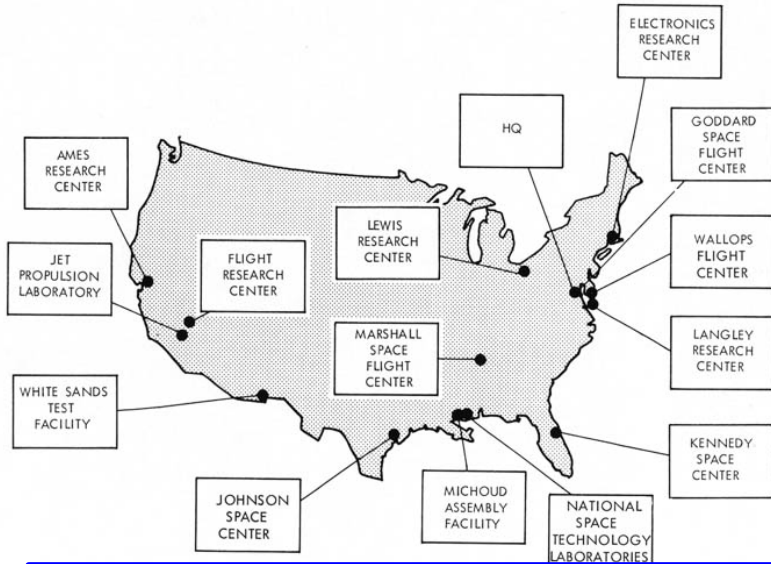
Ethan Shinen Chew

Team Alpha CubeSat

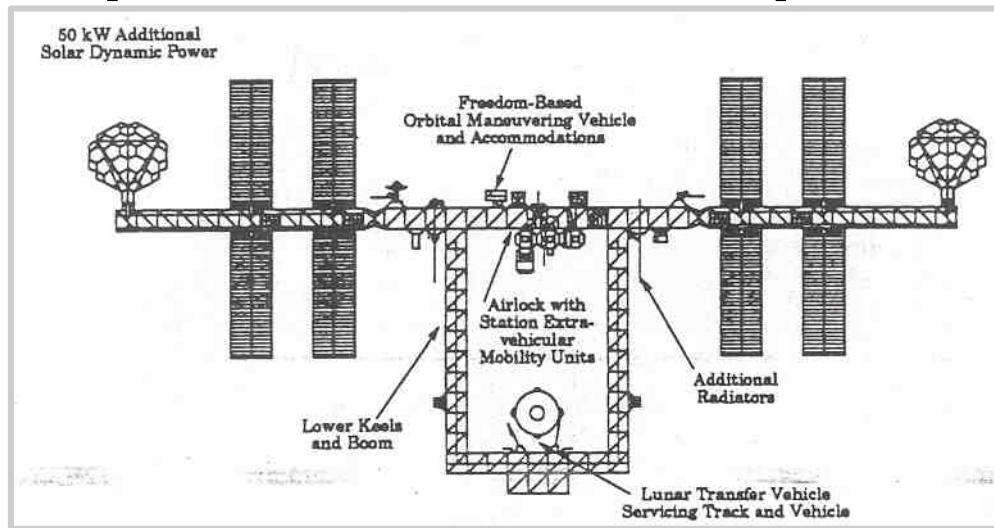
Beyond Earth Orbit

- **Grand designs vs incremental steps**
- **Cislunar space**
- **Potential demonstrations**
- **Alpha Cubesat example: from ISS to lunar orbit**

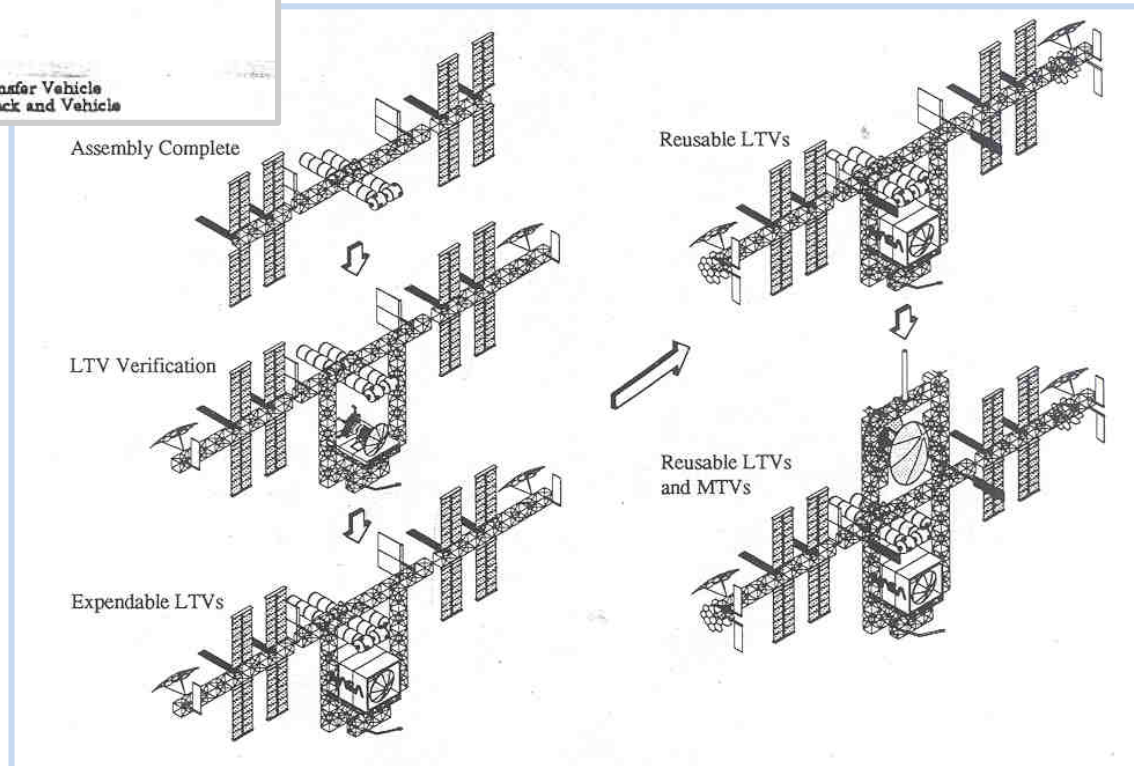
Apollo



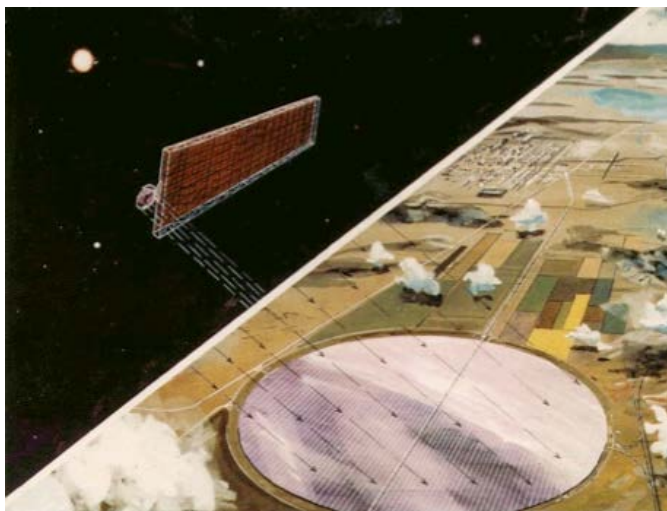
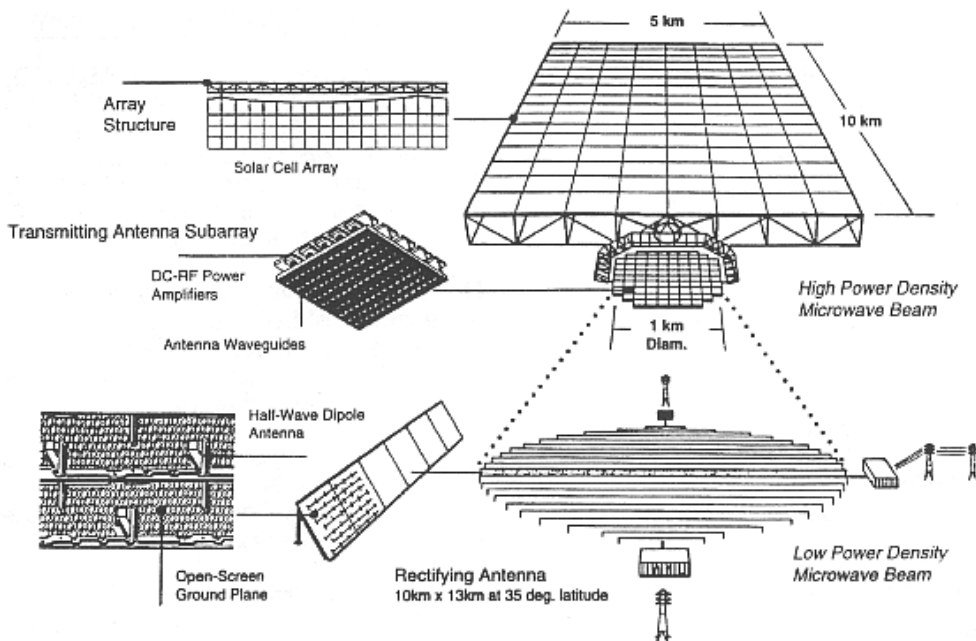
Space Station Transportation Node



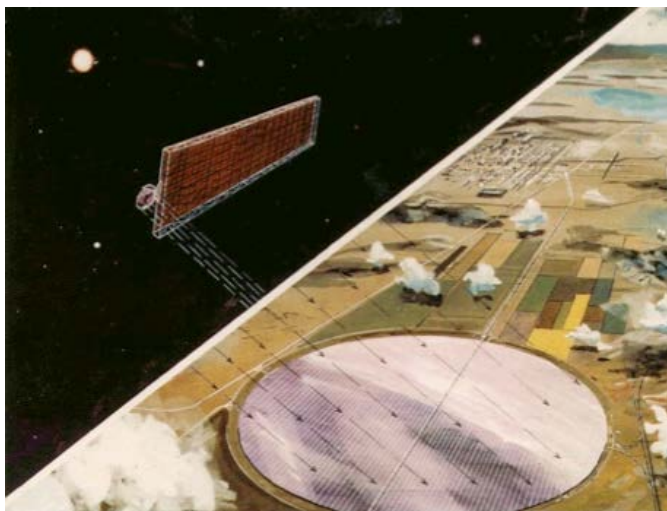
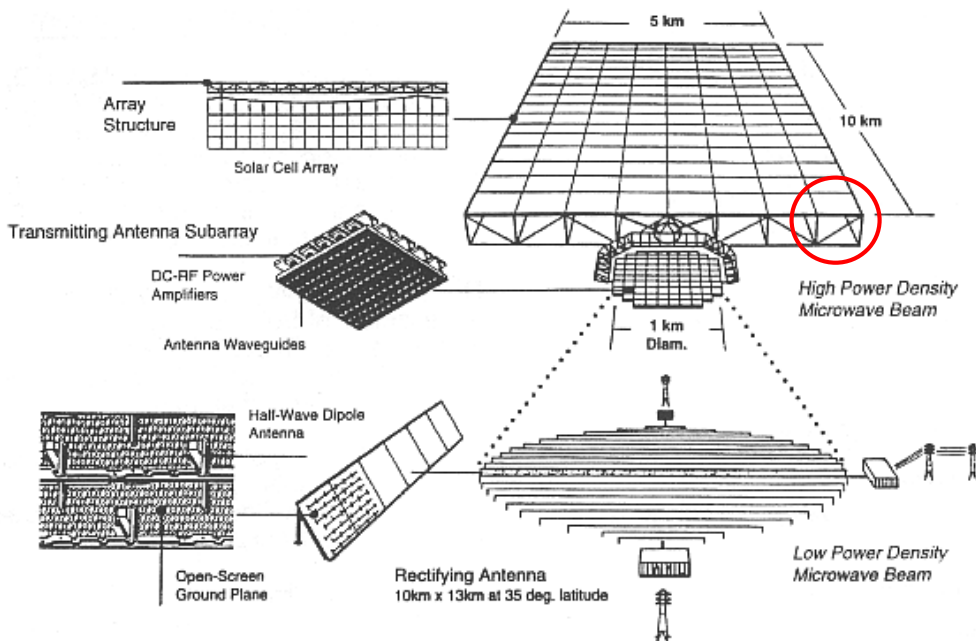
Plans for Space Station Freedom to evolve to become an exploration transportation node (1992)



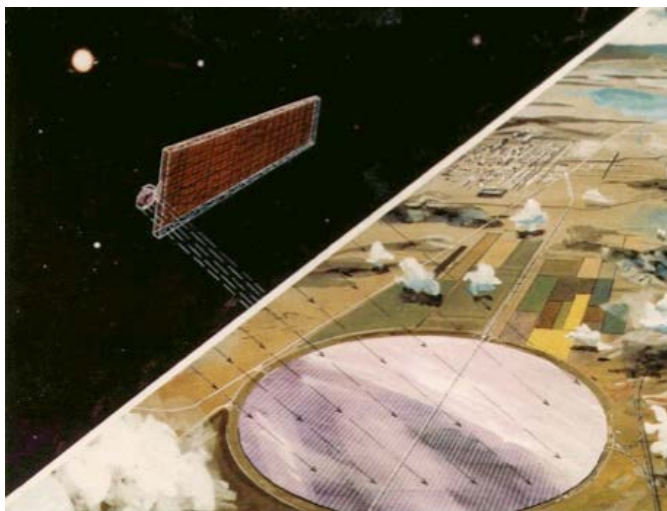
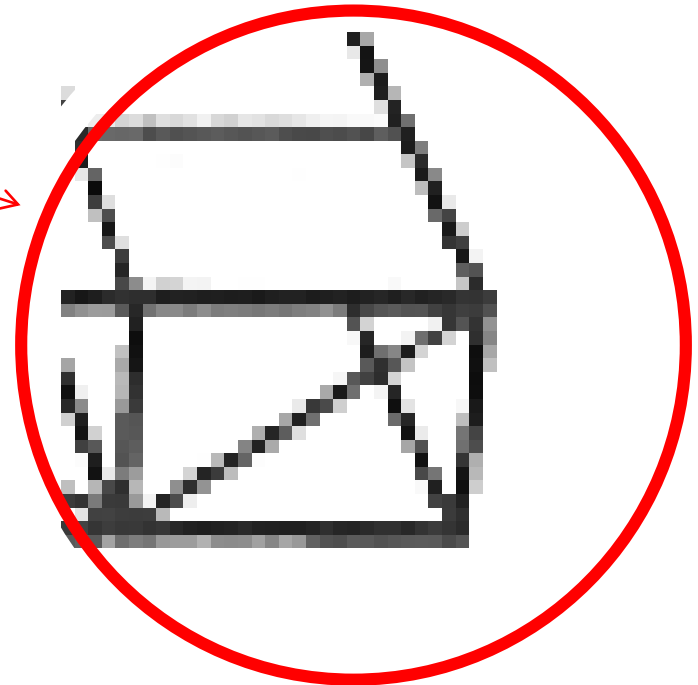
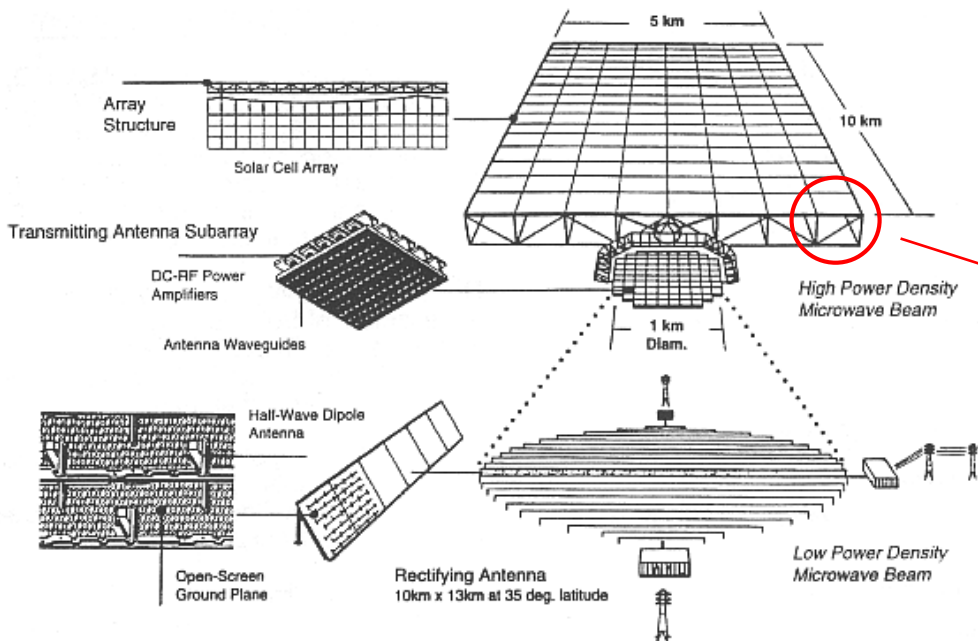
Space Solar Power Satellite design (1980)



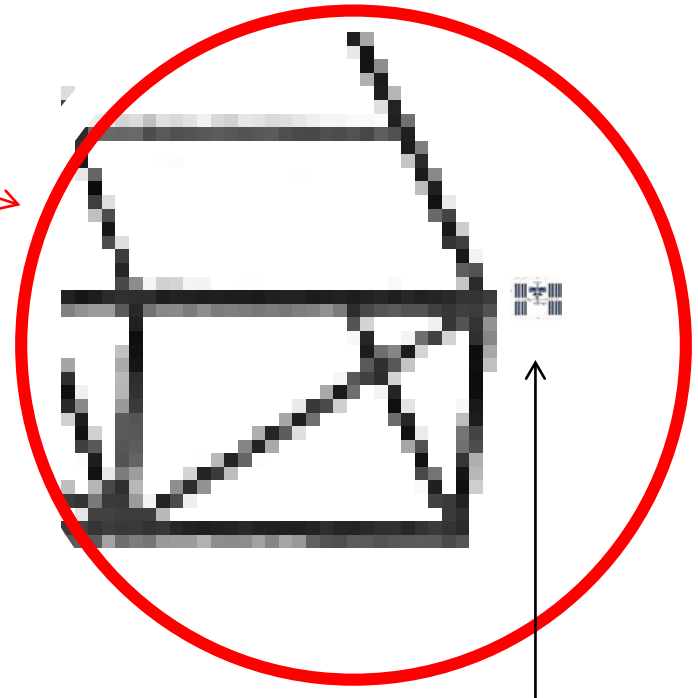
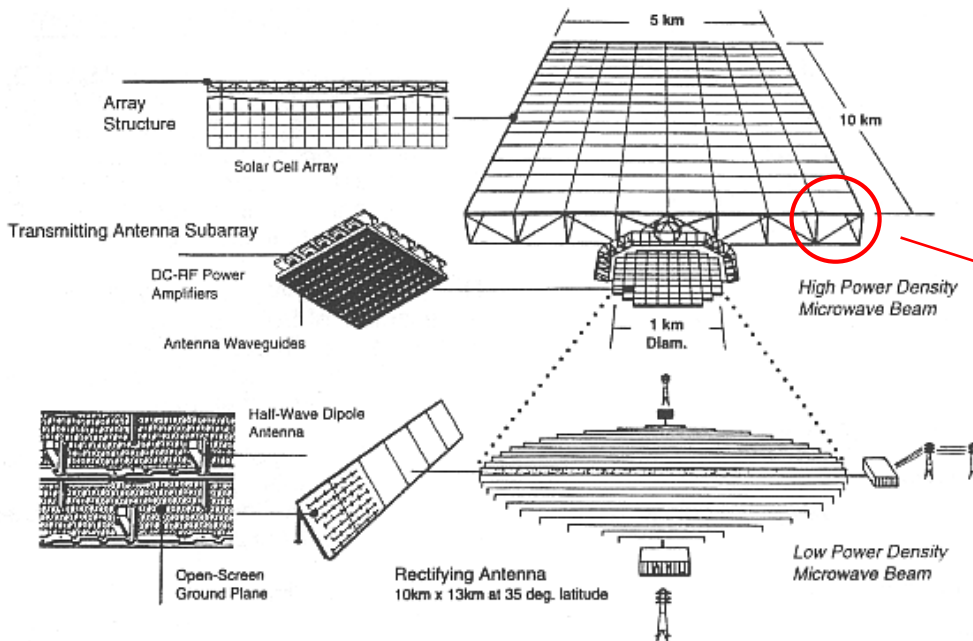
Space Solar Power Satellite design (1980)



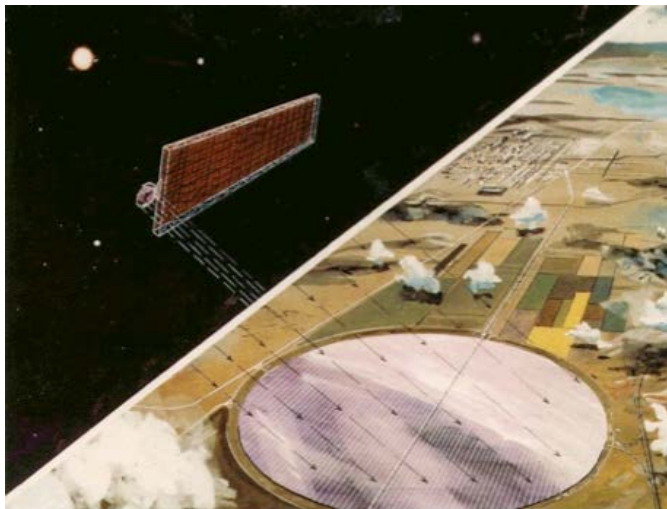
Space Solar Power Satellite design (1980)



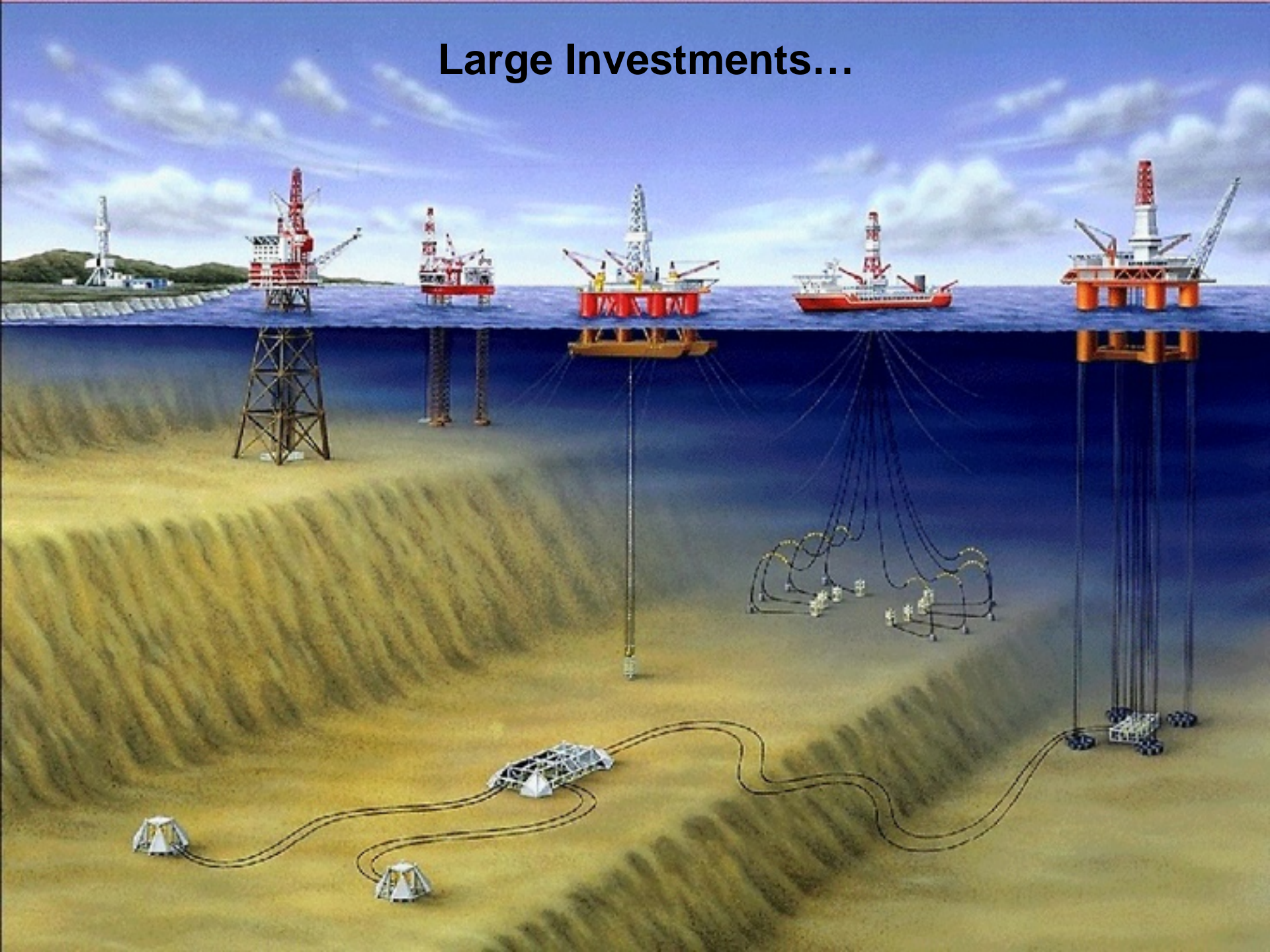
Space Solar Power Satellite design (1980)



**ISS
for scale**



Large Investments...

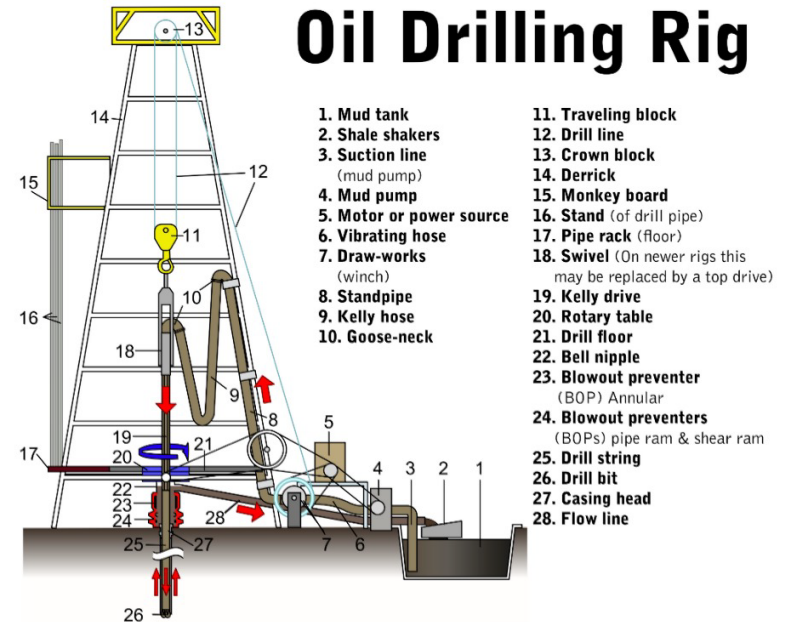
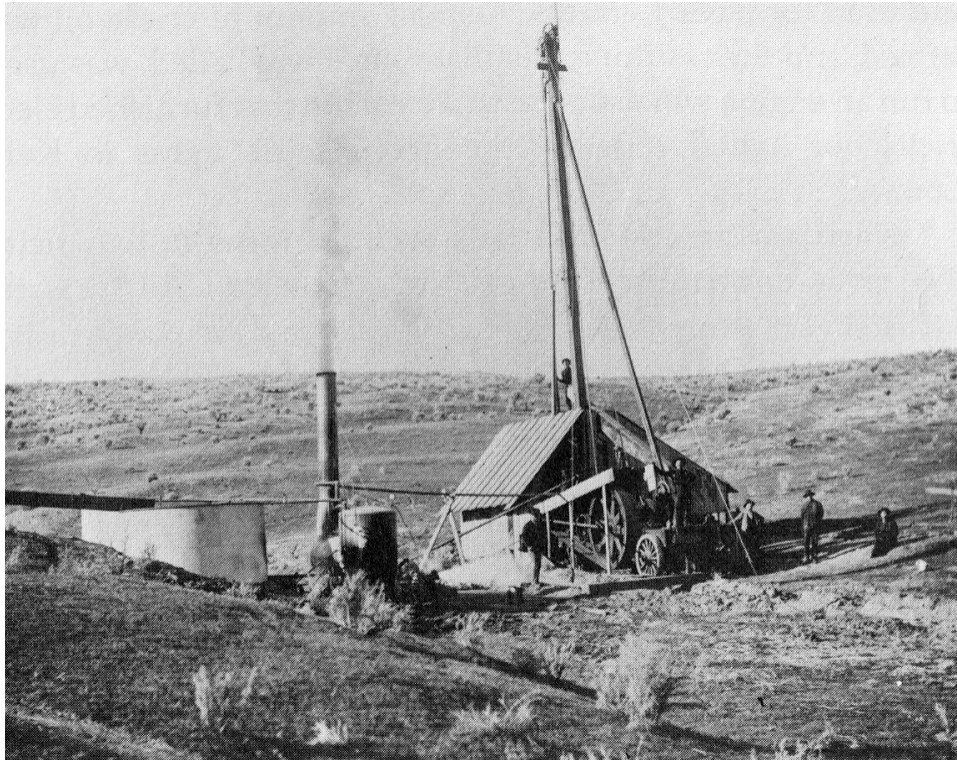


~\$3B for one platform

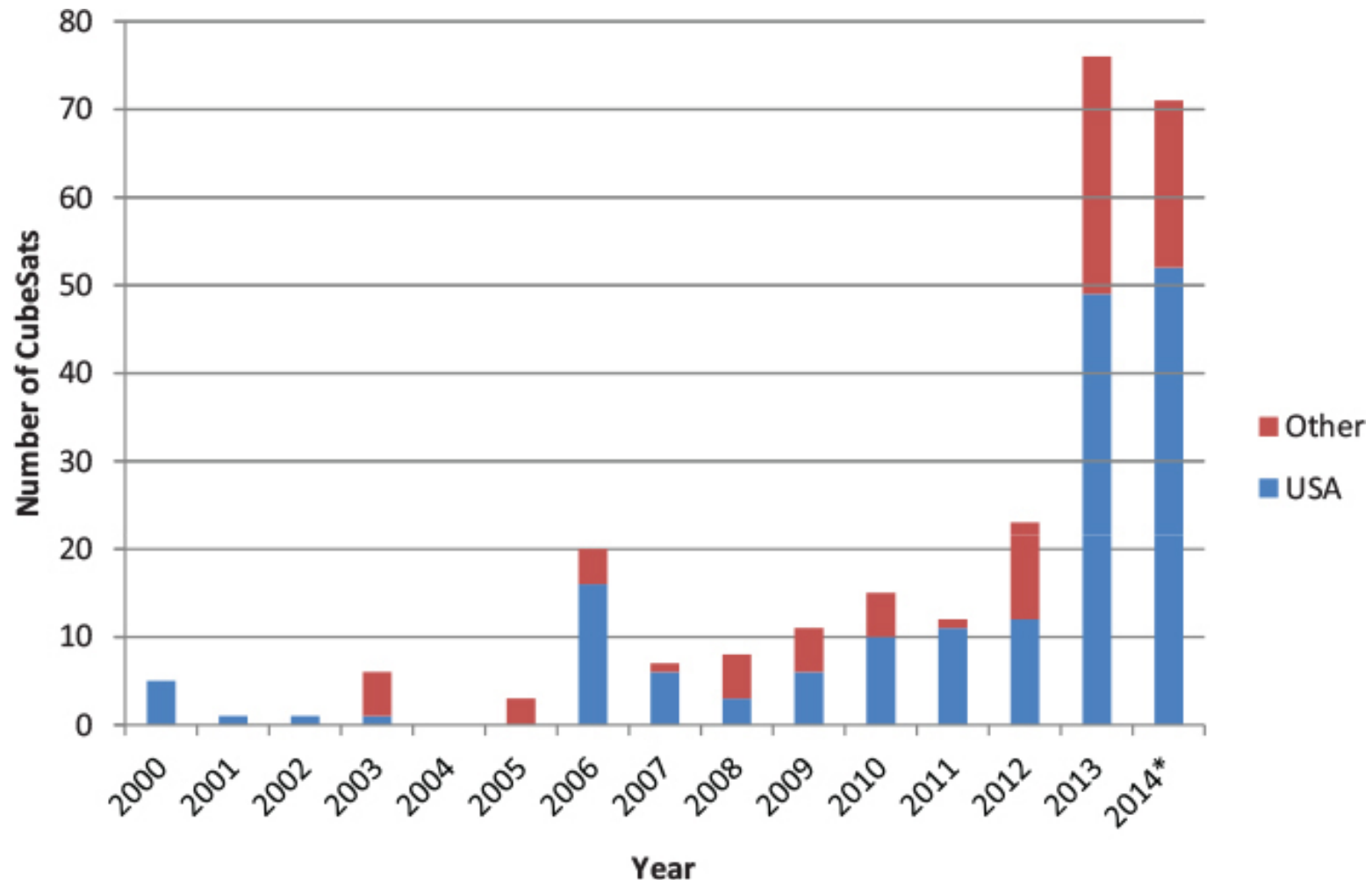
Approaching \$1T invested



...start from simple beginnings



Opportunities for incremental progress



Cislunar Space

radius of Earth: 6,400 km / highest non-lunar human spaceflight: 1,400 km

radius of Moon: 1,700 km



closest perigee: 356,000 km / average: 384,000 km / furthest apogee: 406,000 km



Cislunar Space

Orbits and trajectories

LEO, orbital periods, delta-v, MEO, GTO, GEO, inclinations

Earth environment

atmospheric drag, eclipse periods, orbital debris zones, magnetic field

Radiation

Inner and outer radiation belts, solar flares, coronal mass ejections, solar proton events, cosmic rays

Cislunar trajectories

Earth-Moon Lagrange points, Earth-Sun Lagrange points, orbit transfer manifolds, interplanetary superhighway

Lunar surface

Lunar regions, latitudes, day-night cycle, thermal cycle, dust, landing, liftoff

Asteroids and comets

NEOs, orbital elements, synodic periods, asteroid types, surfaces and structure

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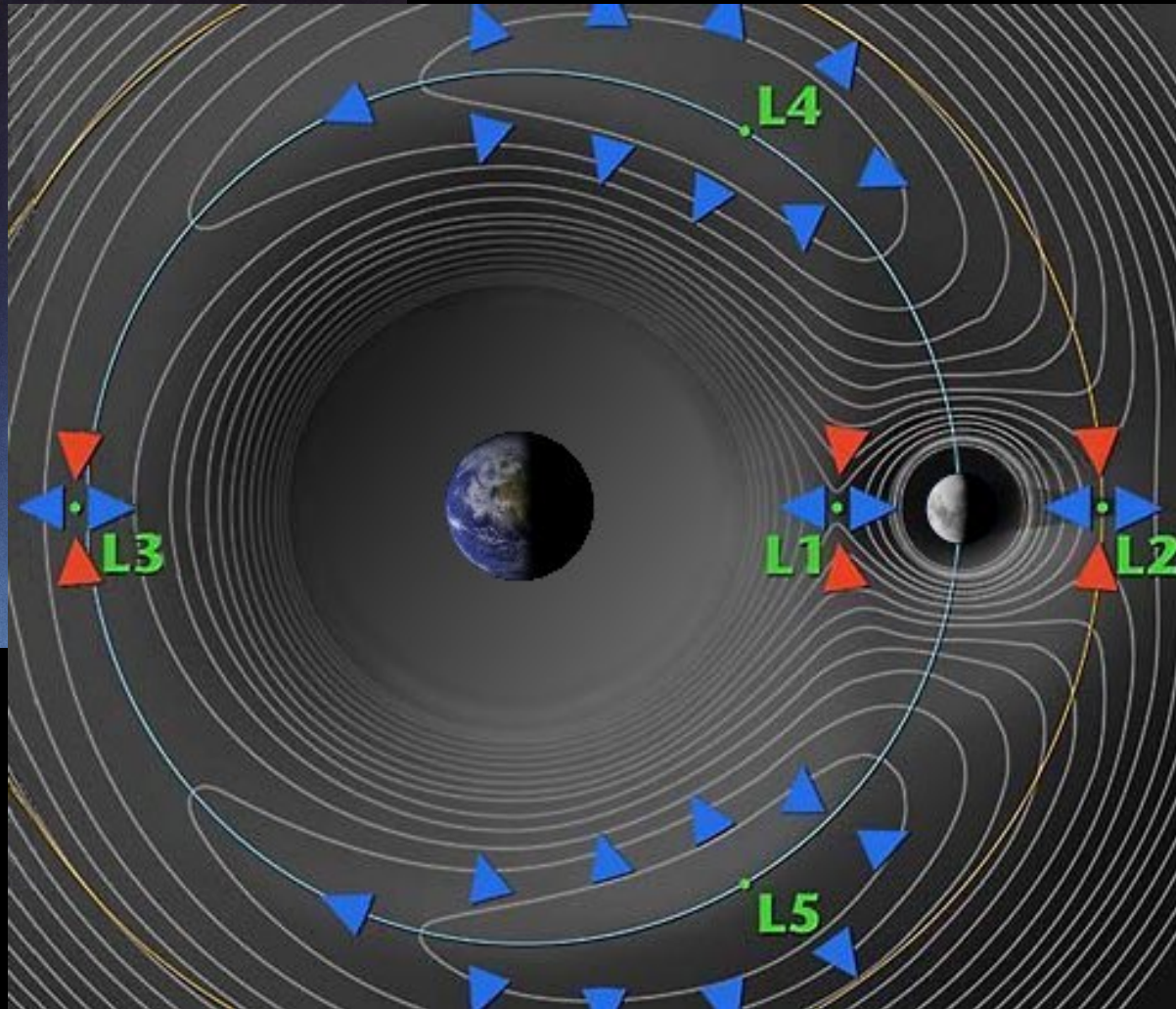
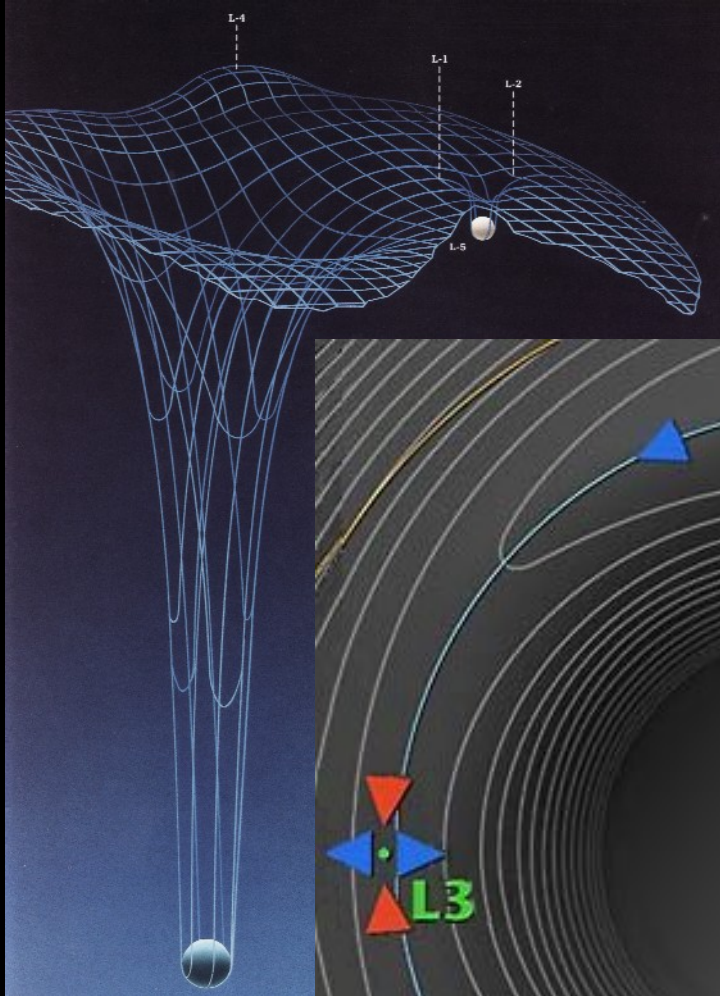
Lunar surface

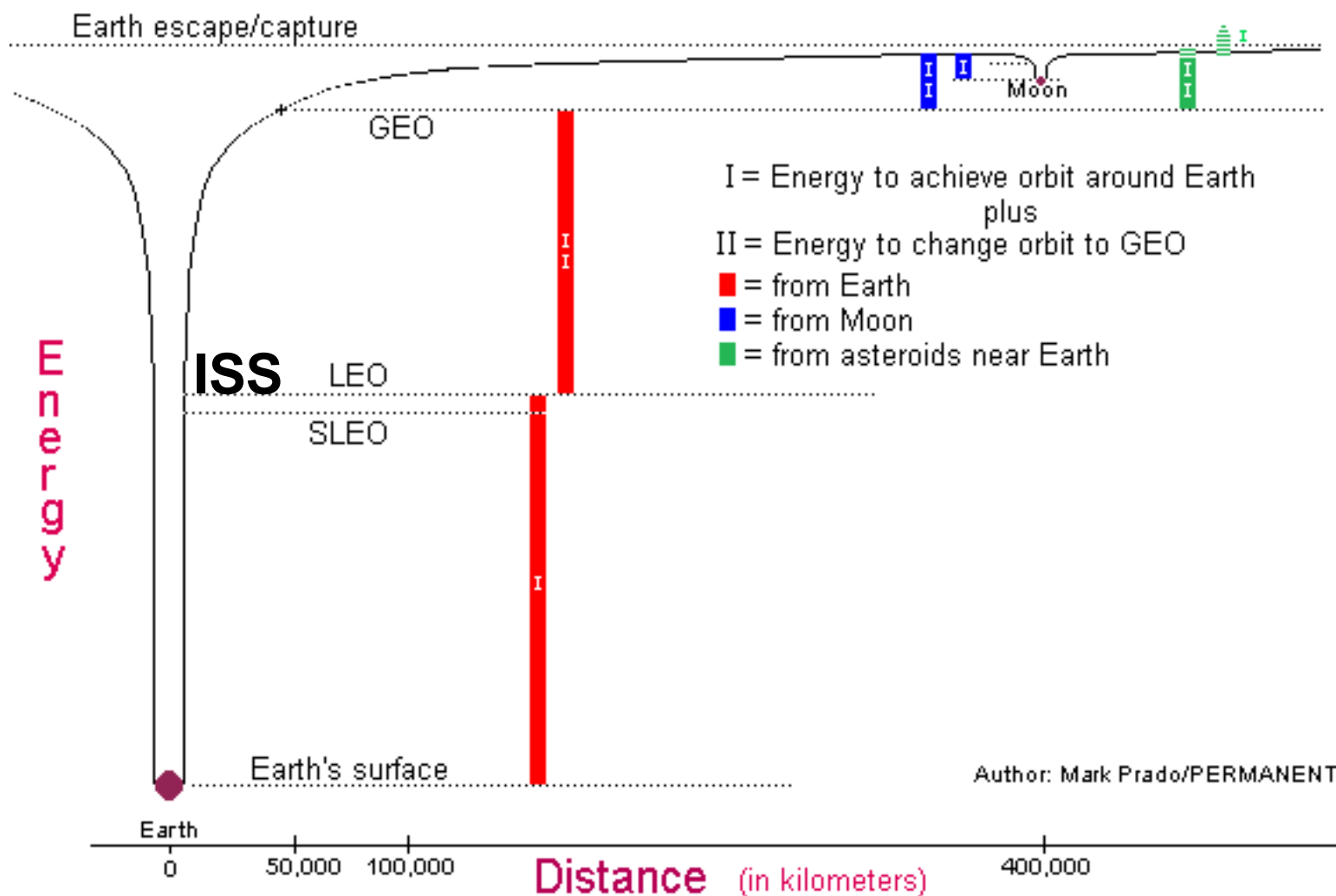
Lunar regions, latitudes, day-night cycle, thermal cycle, dust, landing, liftoff

Asteroids and comets

NEOs, orbital elements, synodic periods, asteroid types, surfaces and structure

Earth and Moon gravity wells and libration points





Earth and Moon separation scaled by delta-v

ISS is 'halfway to anywhere'

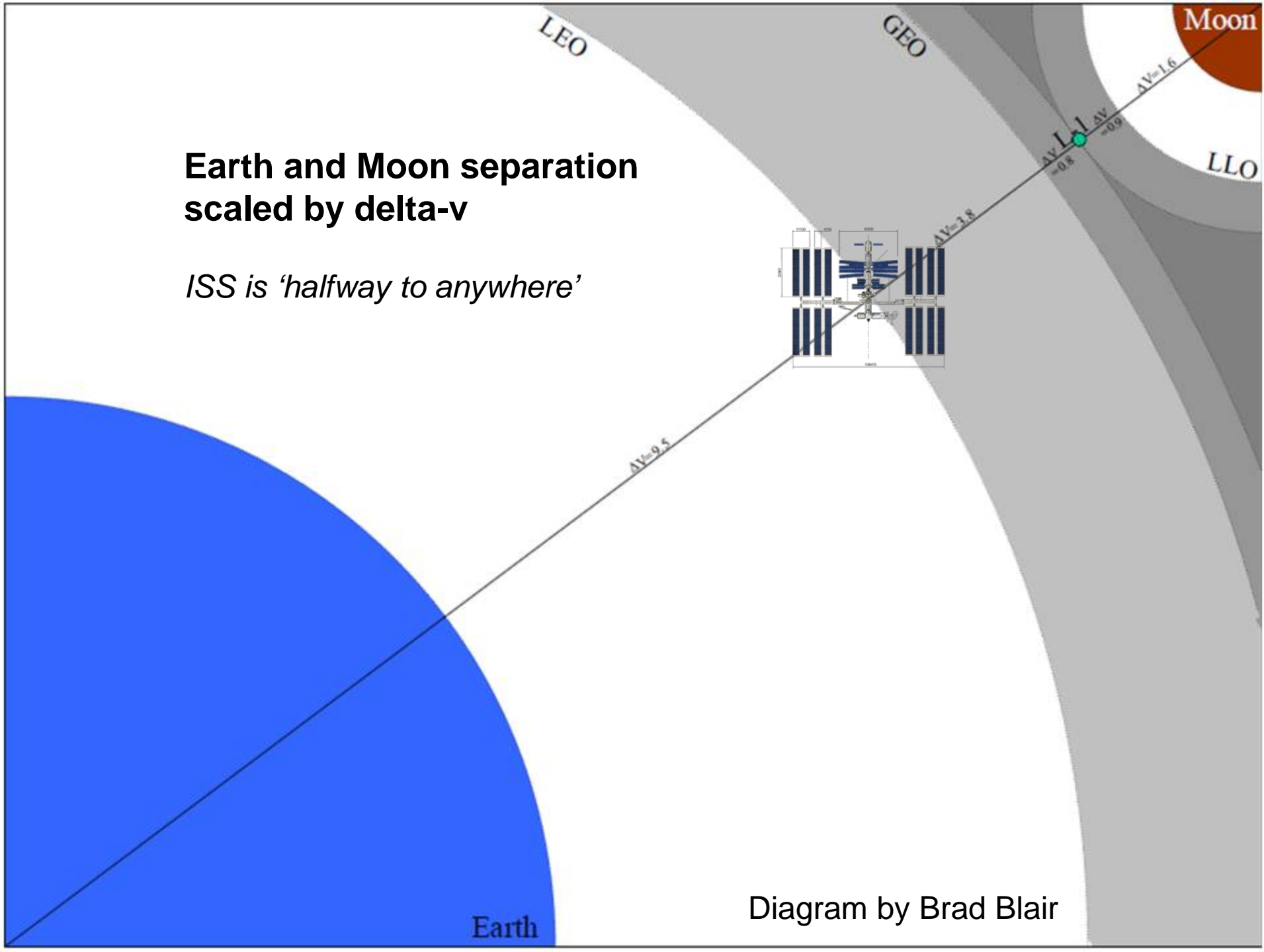
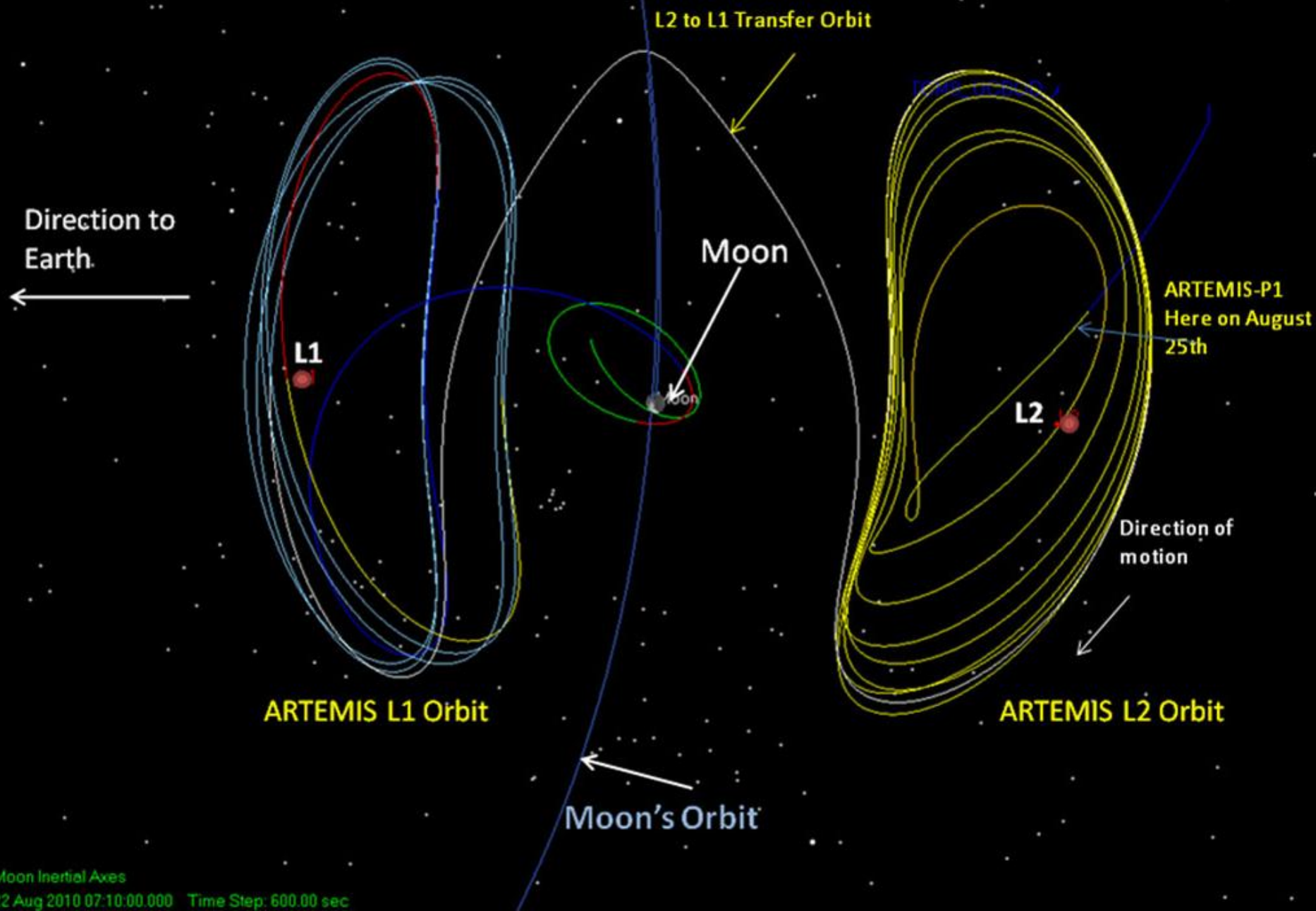


Diagram by Brad Blair

ARTEMIS-P1 Spacecraft's Orbit – Top View



ARTEMIS-P1 Spacecraft's Orbit – Side View

Towards Earth
←

Moon

ARTEMIS-P1 Here
on August
25th

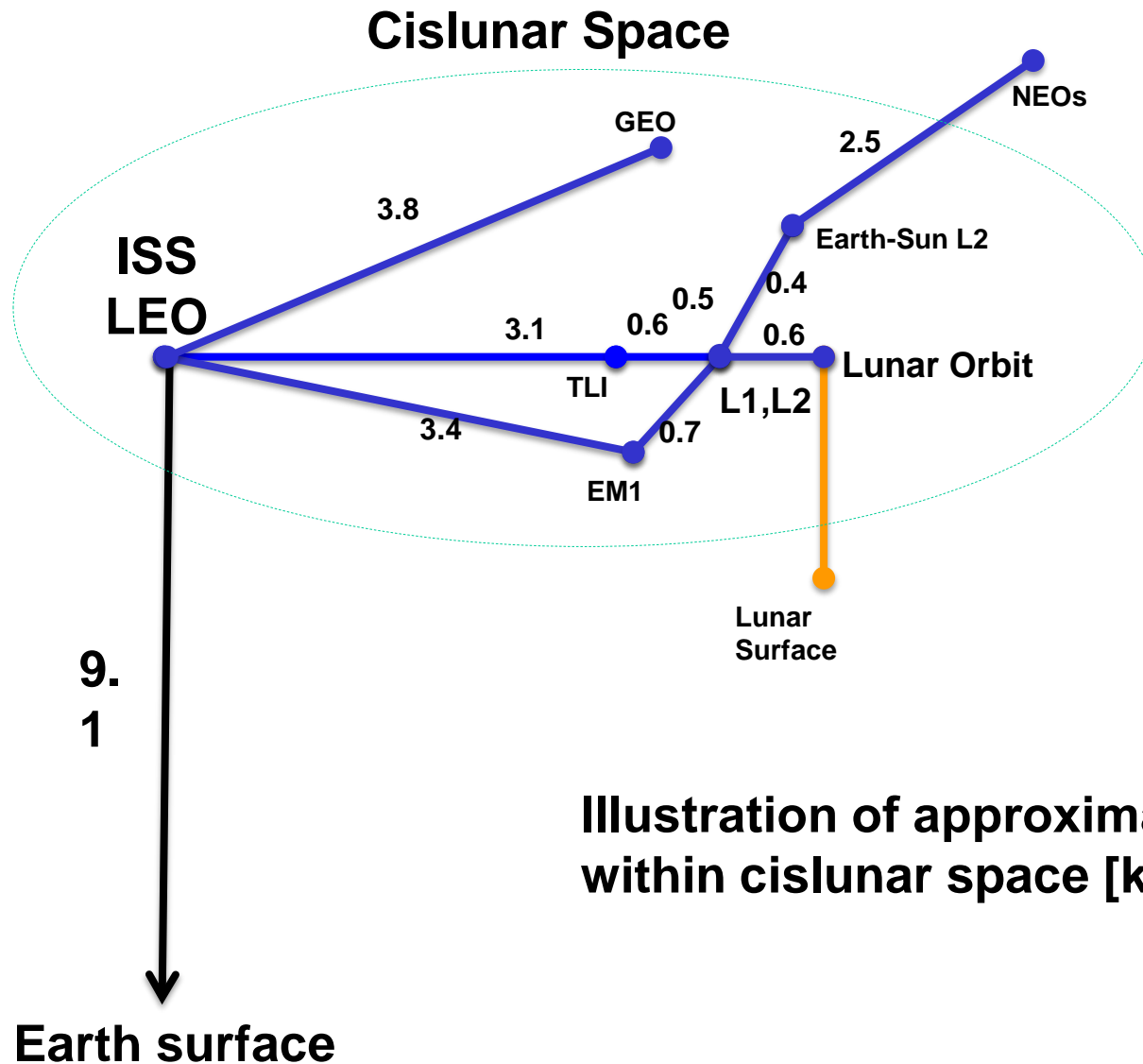
L1

ARTEMIS L1 Orbit

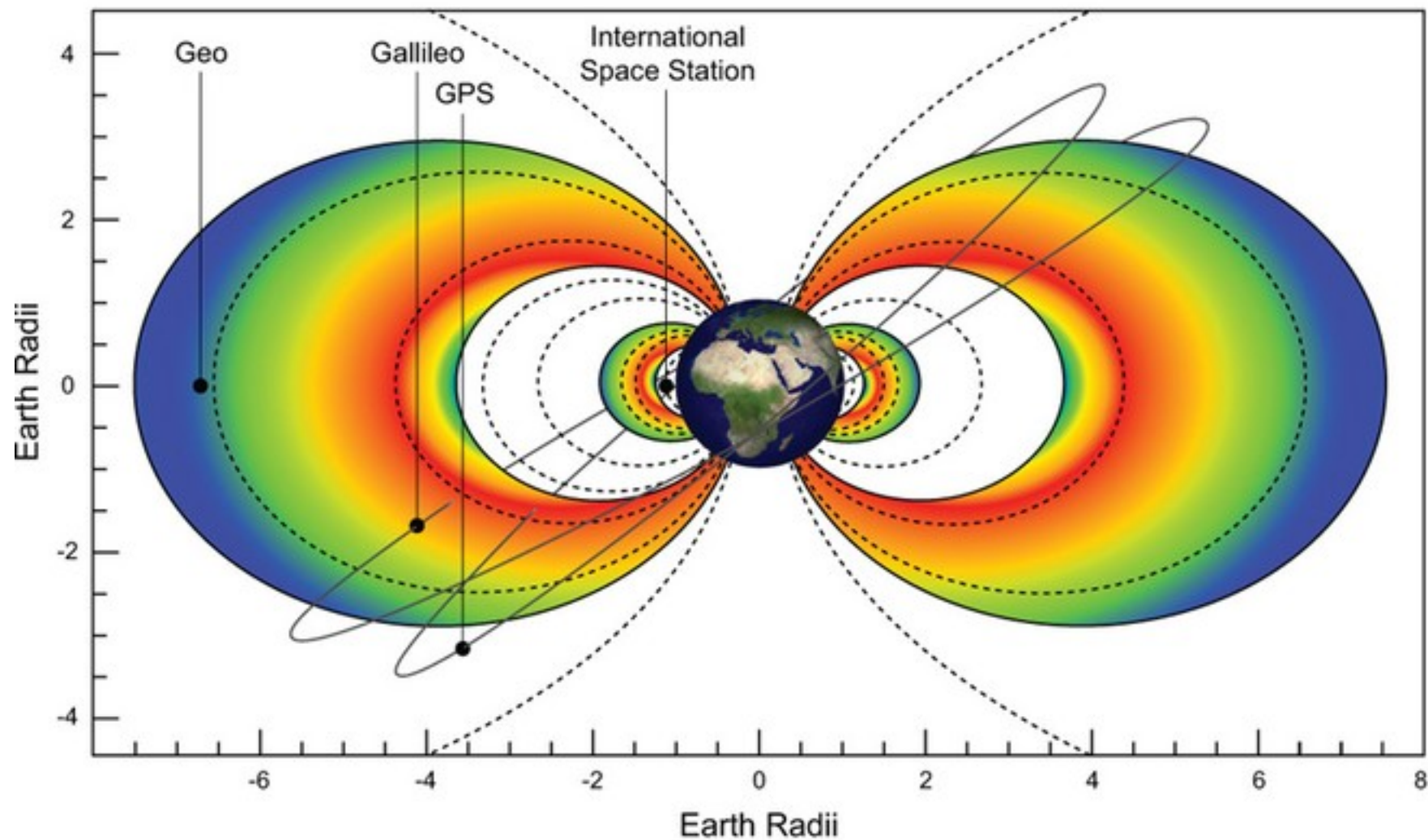
L2

ARTEMIS L2 Orbit

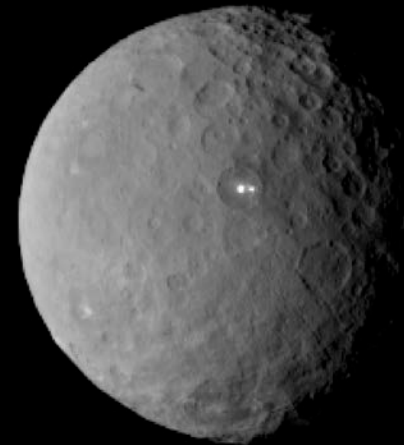
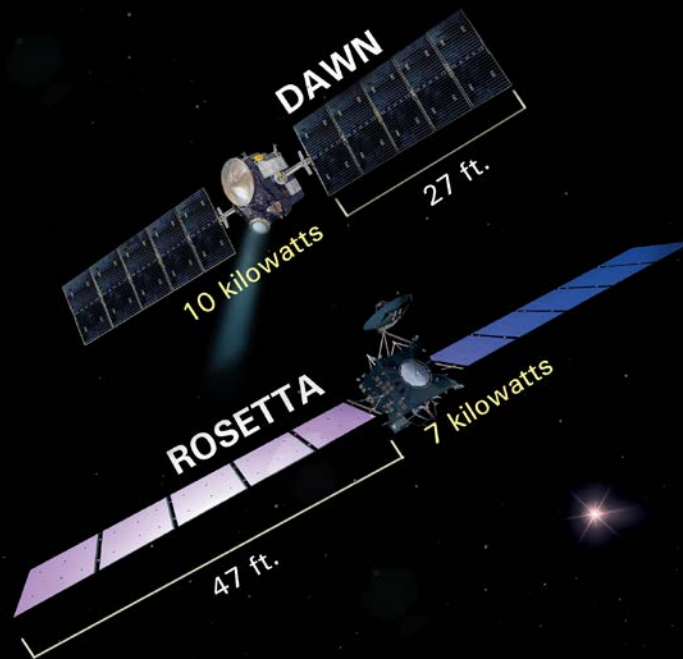
P1_L2_TCM3_UCBOD_Aug2010_51M1_cross_down



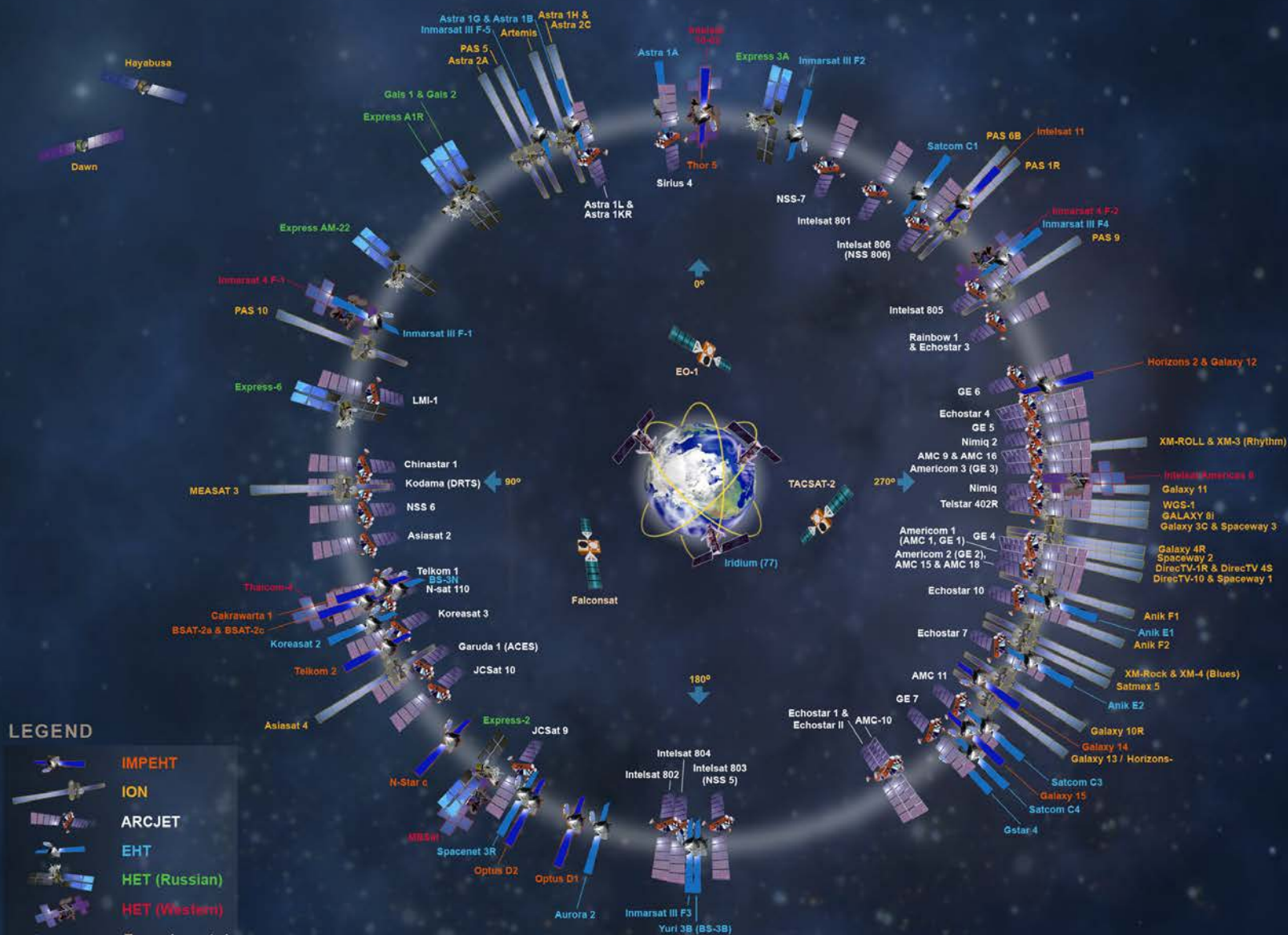
The Earth's Electron Radiation Belts



DAWN



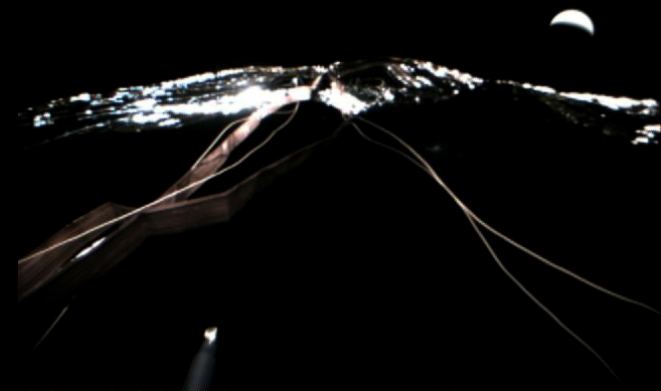
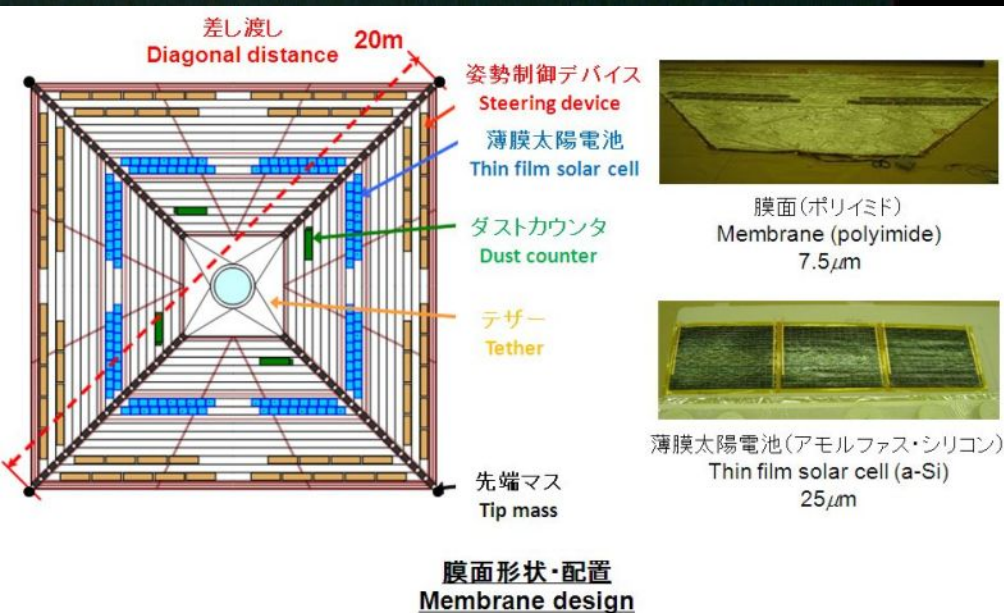
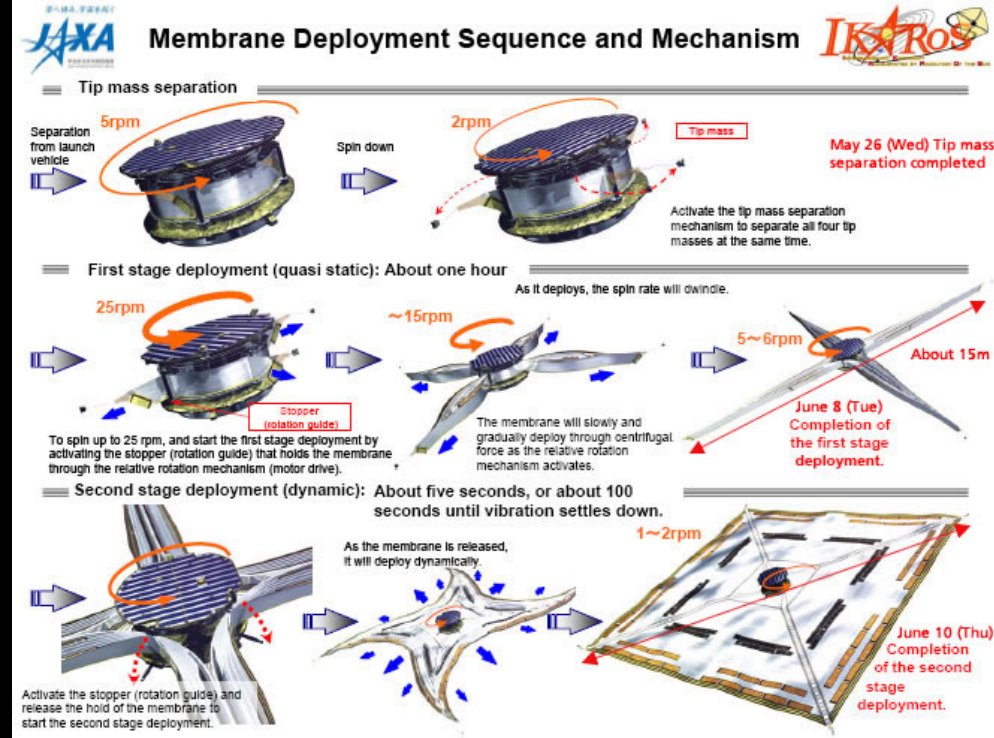
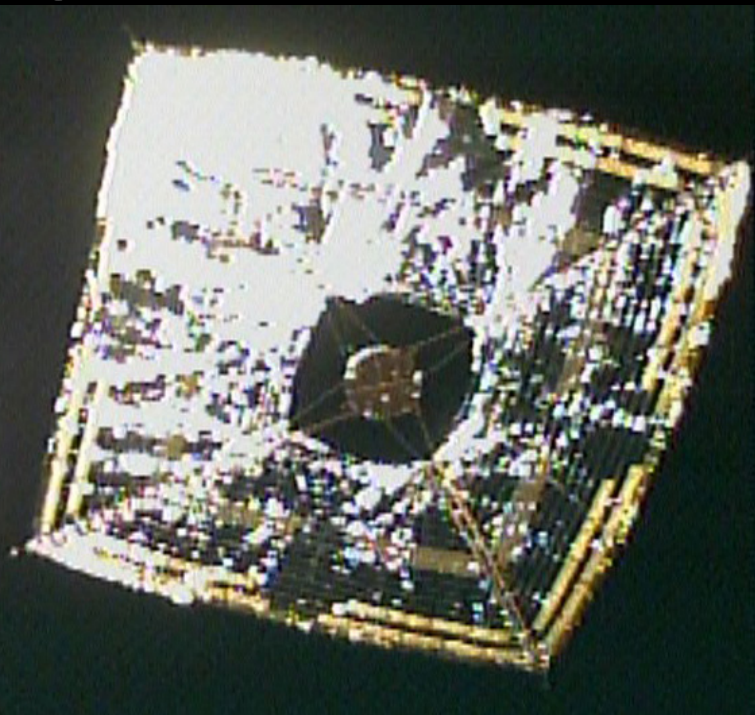
Operational Satellites with Electric Propulsion



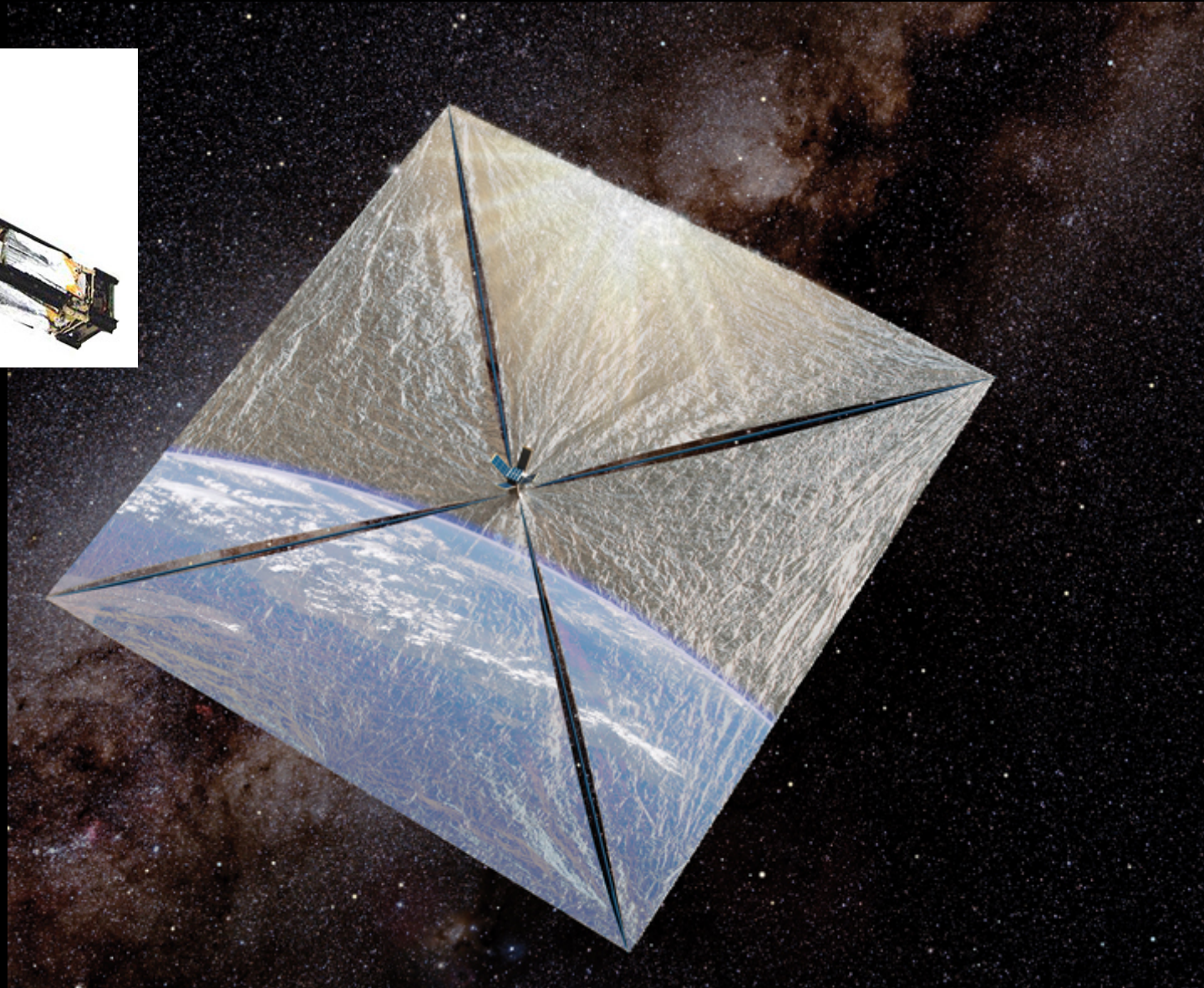
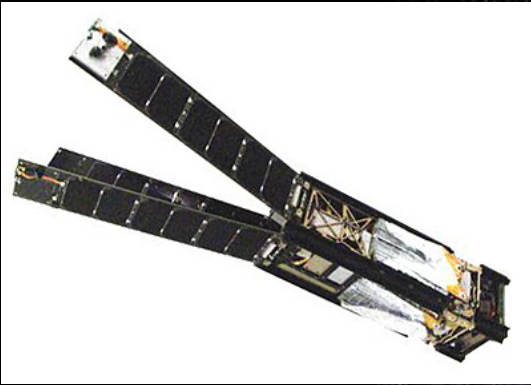
Cumulative Number of Satellites Employing EP = 226
 Number of Satellites Employing Aerojet EP = 156

AEROJET

Lightsail Demonstrations

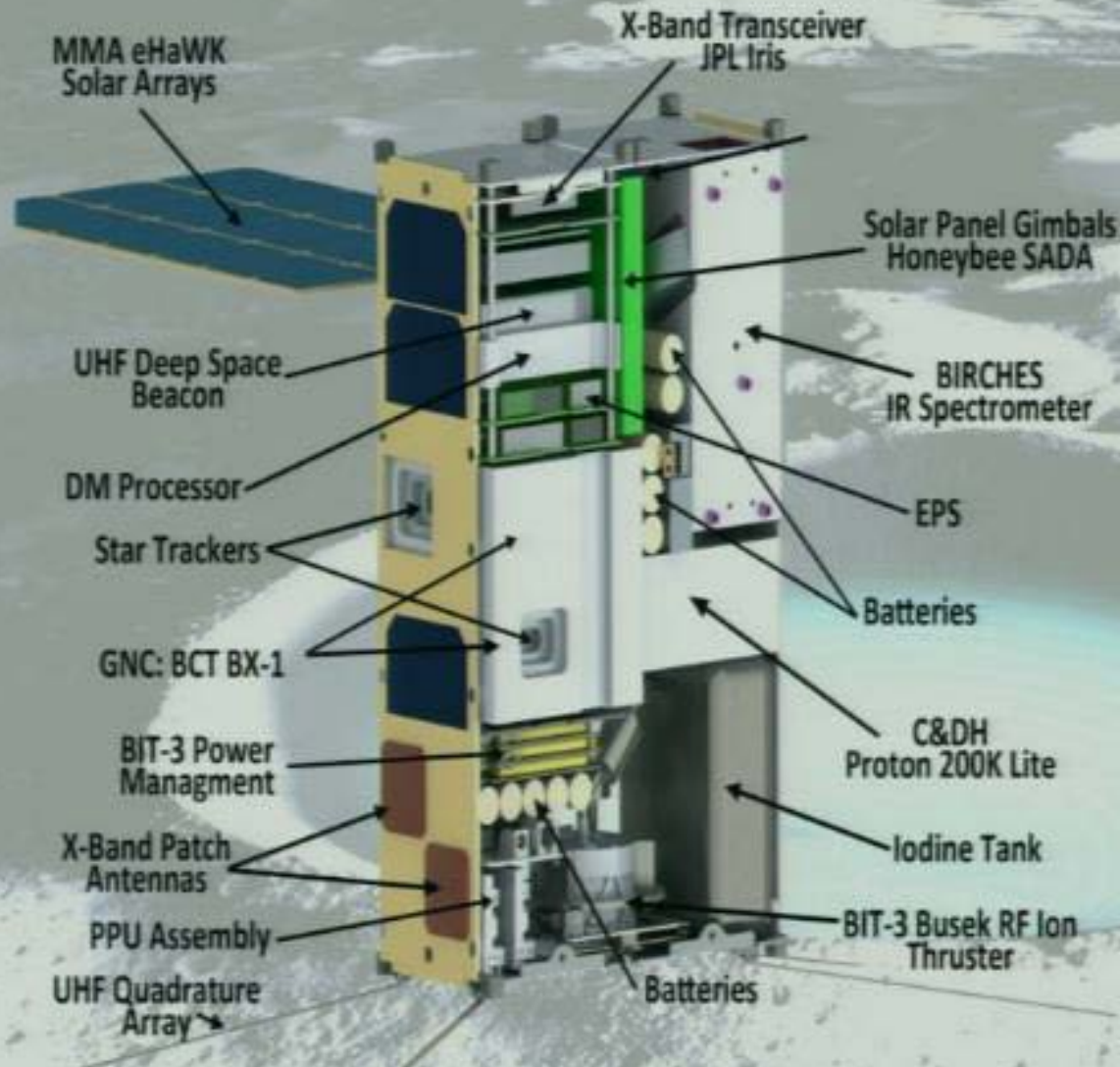


Lightsail Demonstrations

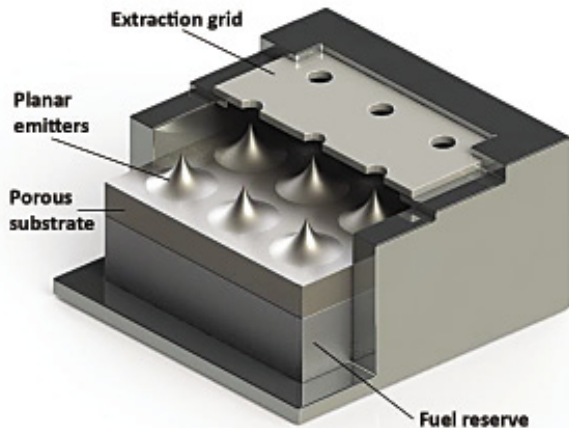


IceCube - Lunar cubesat design

Morehead CubeSat Bus

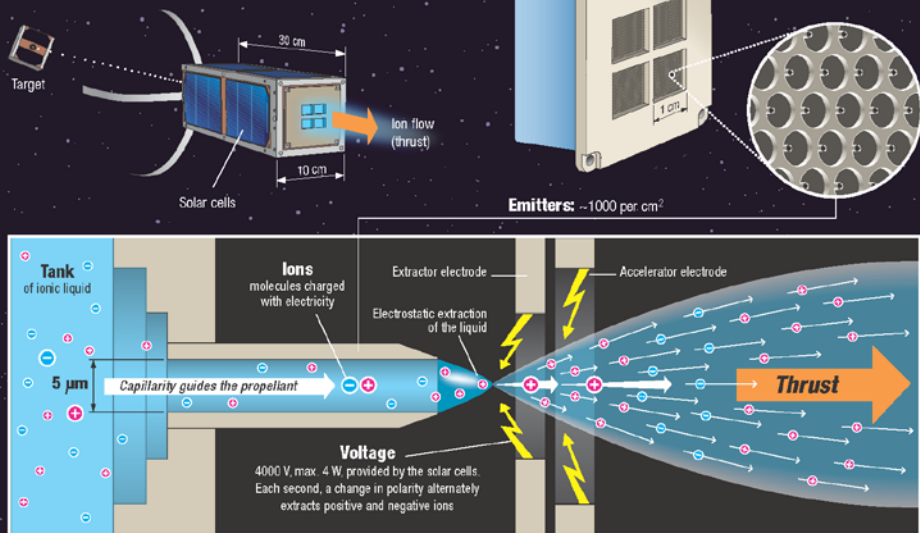


Variety of cubesat propulsion systems being developed



An Ion Thruster for CleanSpace One

The EPFL is leading a consortium developing an ultra-miniaturized ion thruster in the framework of a European research project. With this technology, small satellites will finally be able to autonomously change orbits.



HYDROSTM Thruster

Powerful 'Green' Propulsion for Small Satellites



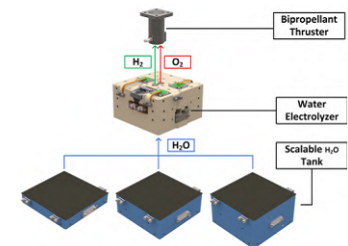
The HYDROS Propulsion System provides orbit agility, precision pointing, and rapid maneuvering to CubeSats and other small satellites. HYDROS is powered by a safe, storable, and non-toxic 'green' propellant – water – which it electrolyzes into hydrogen and oxygen on-orbit, to deliver high-thrust, high-specific impulse propulsion.

Capabilities

Available in 0.5U and 1U configurations delivering:

- Up to 0.8 N of thrust at 300 seconds of I_{sp}
- 100-300 m/s ΔV for a 3U CubeSat
- 50-150 m/s ΔV for a 6U (scalable to >2 km/s!)
- Safe, inert and non-toxic water propellant enables CubeSats to launch as secondary payloads without endangering primary payloads
- Easily expandable water tank for increased ΔV
- Versatile bipropellant microthruster is capable of pulsed hot and cold gas operation
- Water electrolyzer is designed for zero-g operation and inherently separates gases

System Overview



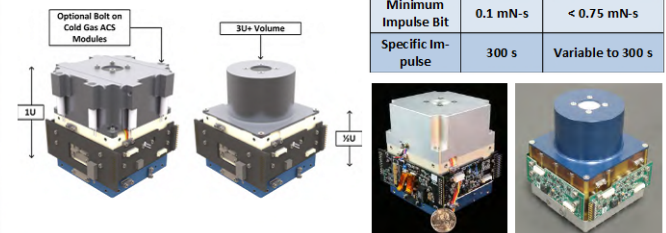
Attitude Control Module

- The HYDROS Thruster is designed to be augmented with a cold gas attitude control system
- Uses hydrogen and oxygen already available from water-electrolysis

Performance

- Technology is current at **TRL-5** and maturation to **TRL-6** is expected by Oct 2014

Performance Metric	Goal	Demonstrated To-Date
Thrust (Max)	1 N	0.8 N
Minimum Impulse Bit	0.1 mN-s	< 0.75 mN-s
Specific Impulse	300 s	Variable to 300 s



Cubesats deployed from ISS



Advantages & Disadvantages - 1

Spacecraft design:

- Assemble at ISS (IVA or EVR in LEO)
- Avoid aerodynamic loads
- Avoid launch loads
- Potential for large structures
- Design for vacuum
- Pure 'space' spacecraft

***Different level of design optimization -
optimize for in-space use***

Advantages & Disadvantages - 2

ISS serves as a Propulsion Test Bed for many options:

- **bi-propellants (non-toxic, non-hazardous)**
- **solar electric/ion thrusters**
- **power beaming**
- **resistojets (e.g., scavenged water, methane, etc.)**
- **mono-propellants (non-toxic, non-hazardous)**
- **solar sails**

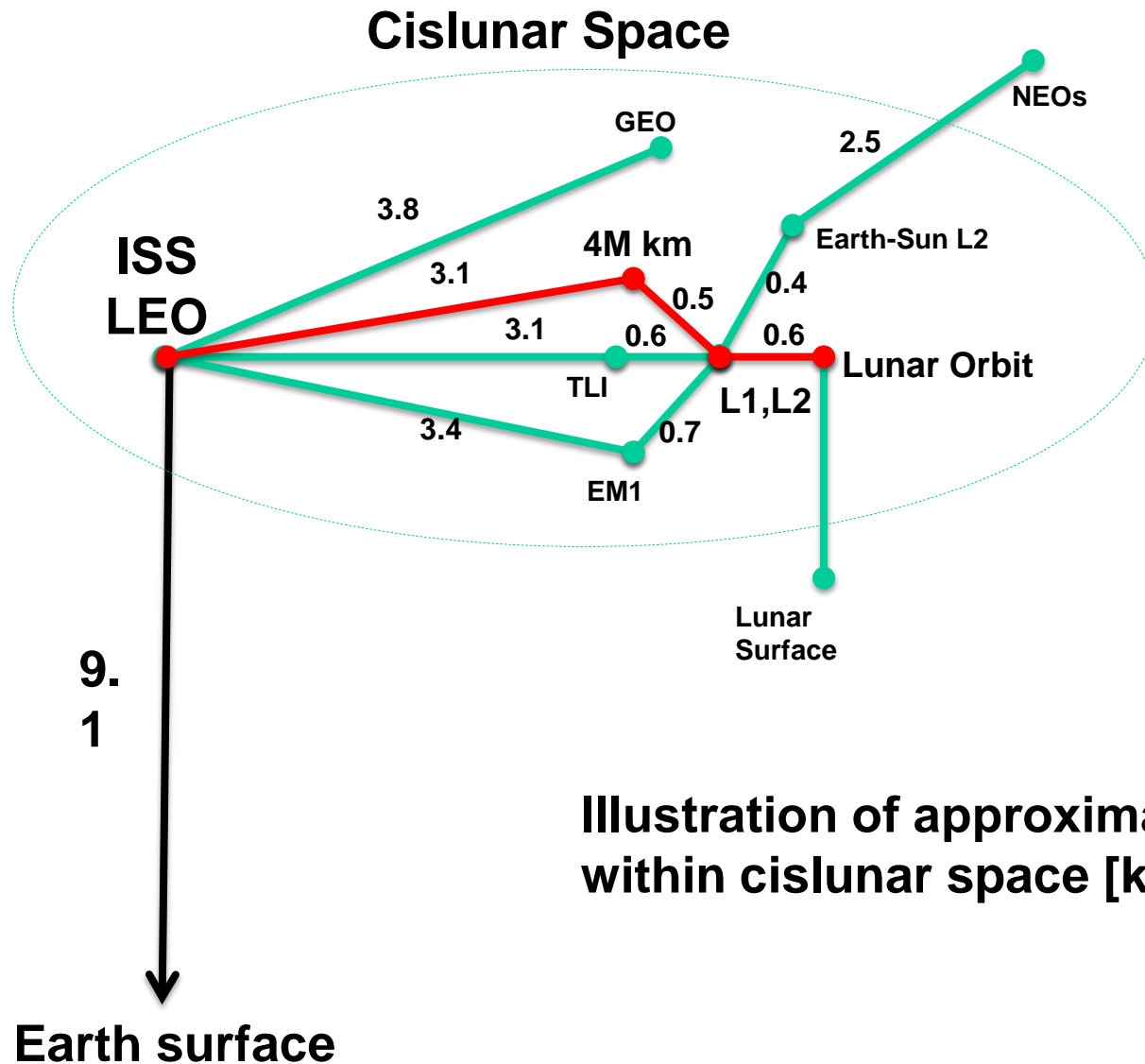
***Provides for a wide range of
low and high thrust options***

Advantages & Disadvantages - 3

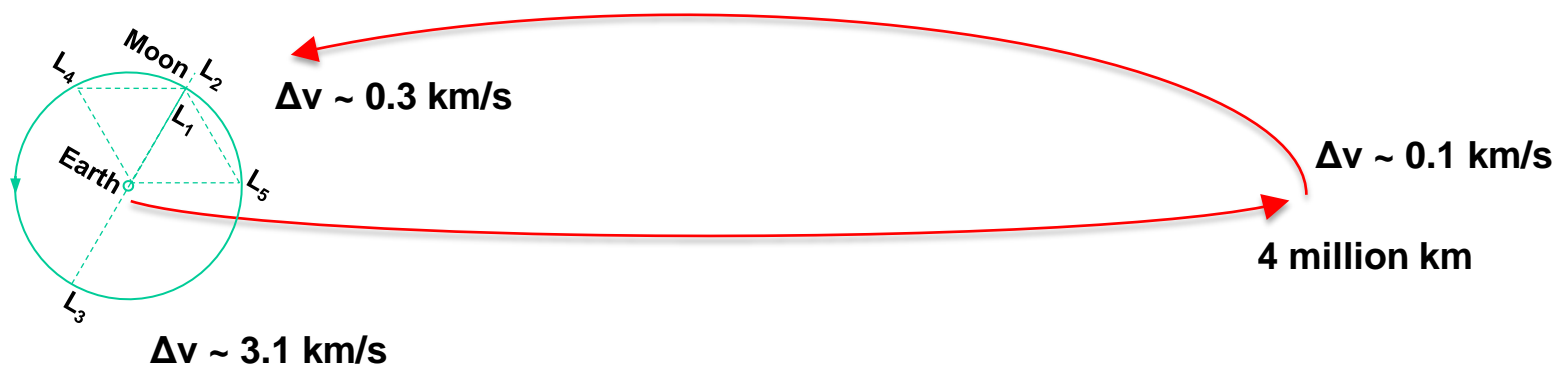
Trajectory and delta-v implications of starting from LEO:

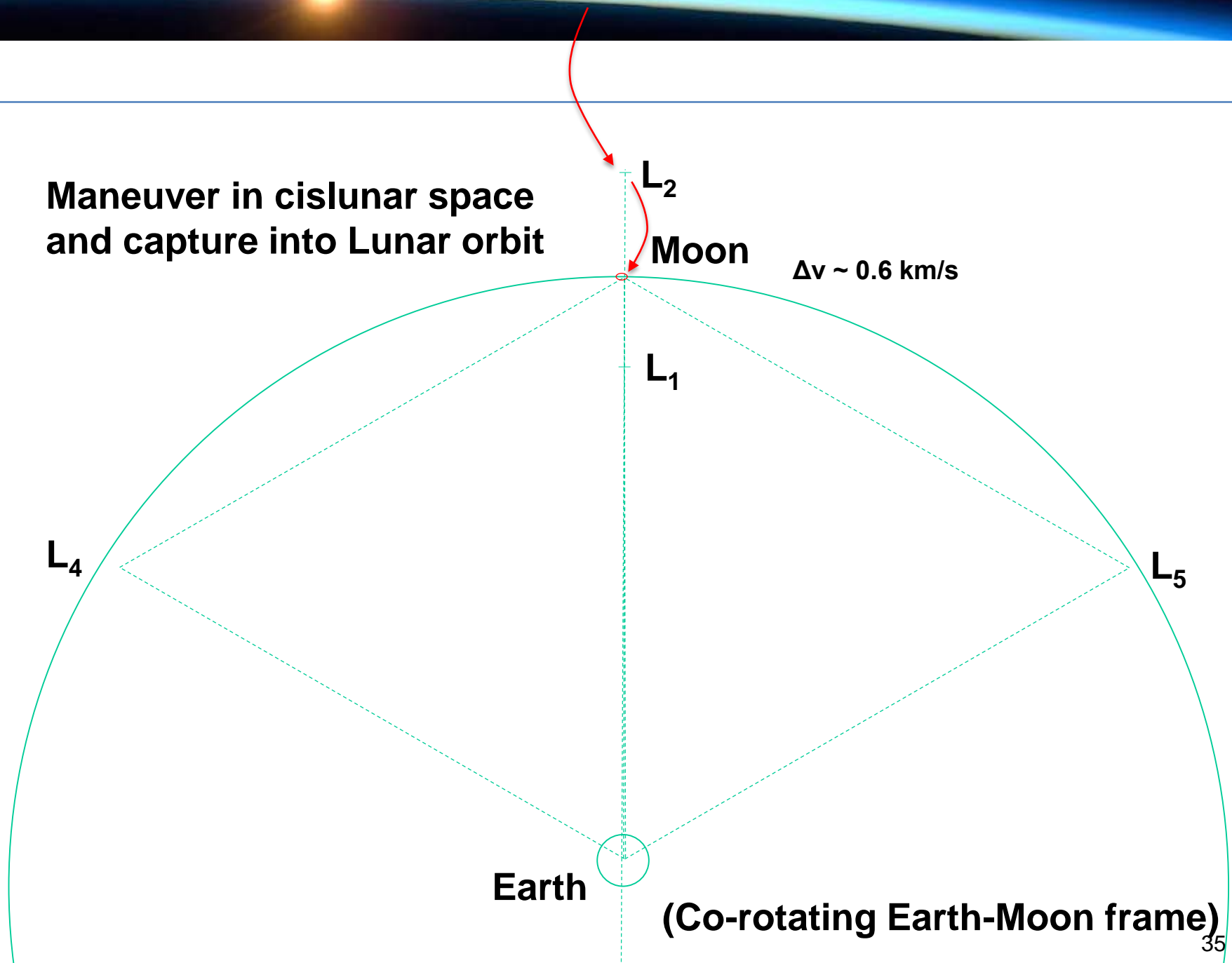
- Classic “minimum” energy trajectories are not optimal
- Alternate minimum energy trajectories become tractable
- Longevity of spacecraft components more critical
- Non-protected orbit transfers increases exposure time to
 - Orbital debris
 - Radiation belts
- The calculations required are more demanding and must be readily accomplished

Alpha Cubesat example: From ISS to 4M km, then LLO



Example: Cubesat from ISS to 4M km, then LLO





ISS as a Launch Platform

- **Commercial Cargo Pressurized “Softpack” launch & stow**
 - IVA unpack & final assembly
 - CYCLOPS JEM Airlock IVA → EVR Transition
 - EVR handoff to Mobile Servicing Centre (MSC)
- **Commercial Cargo Unpressurized Cargo launch & stow**
 - EVR unpack & final assembly
 - EVR handoff to Mobile Servicing Centre (MSC)
- **Support services**
 - EVR MSC relocate & position for deployment
 - MSC SPDM Deployment RAM + Starboard + Zenith Bias
 - Final proximity checkout services (e.g., imaging, communications, navigation & power)

Zenith / Away from Earth

Wake / Aft

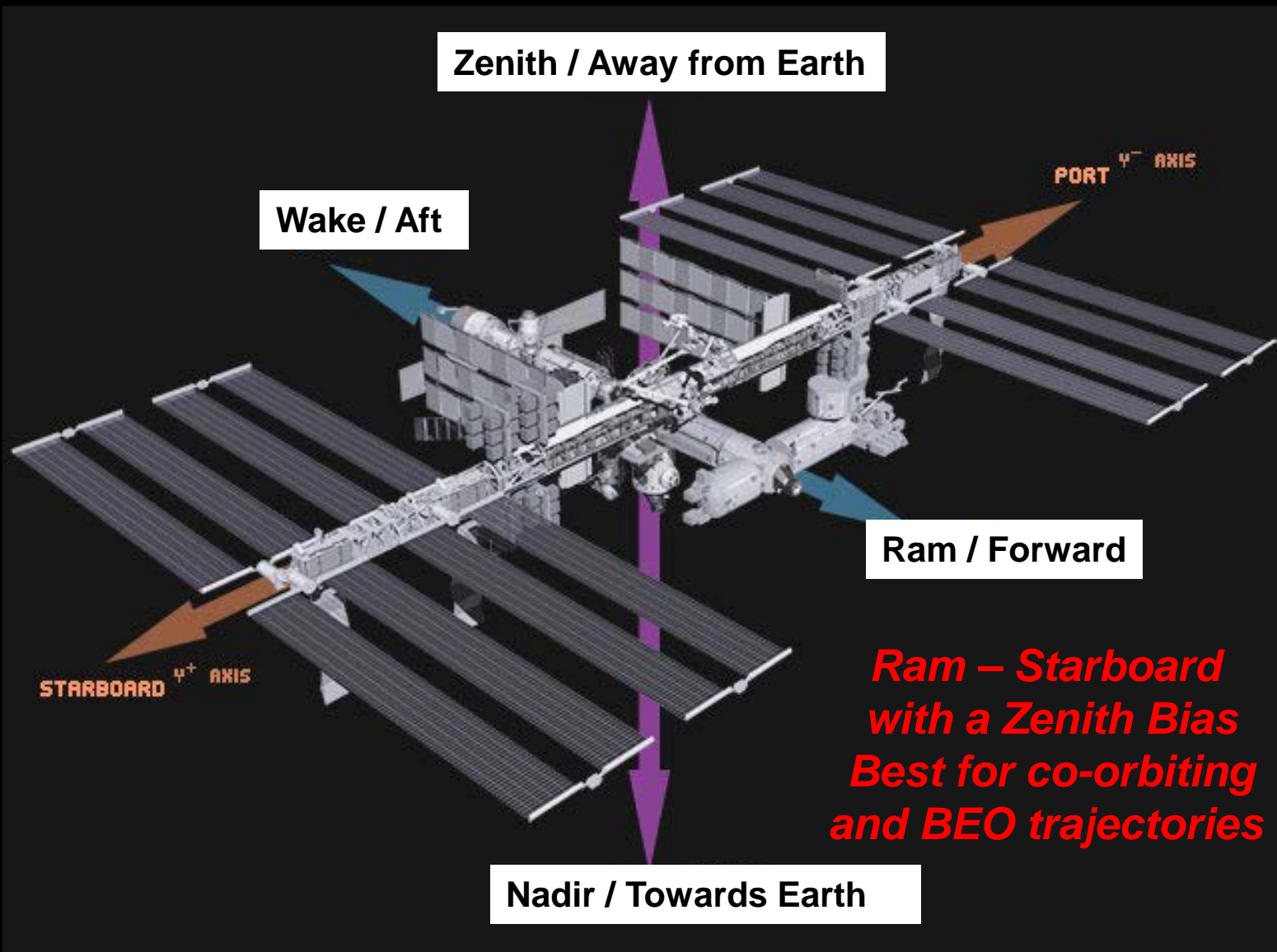
PORT ψ^- AXIS

Ram / Forward

STARBOARD ψ^+ AXIS

*Ram – Starboard
with a Zenith Bias
Best for co-orbiting
and BEO trajectories*

Nadir / Towards Earth



Conclusion

- **Multiple solutions exist for ISS launch in theory, in practice we need to test & optimize alternatives**
- **We need to learn how to scale to larger systems**
- **We need to create opportunities for collaboration**
- **We need to find ways to do more with less resources**
- **On-orbit final assembly and checkout needs to be move from theory to practice**

***This is a new way of doing business,
that we need to learn to leverage . . .***

Next Steps

- Design and implement a propulsion testbed environment for ISS
 - Testbed will provide the common infrastructure required
- Safety protocols required for each mission stage must be defined
 - Experiments need a known path to flight
- Each experiment will start with the defined operations and safety protocols augmented as needed based on any mission unique aspects added
- The possibilities for final assembly and checkout support need to be actualized by based on meeting real mission requirements

***“Once you're in low Earth orbit
you're halfway to anywhere.”
– Robert Heinlein***